

36. The resultant velocity of the airplane is the sum of the velocity of the airplane and the velocity of the wind.

$$\mathbf{r} = \mathbf{p} + \mathbf{w} = \begin{bmatrix} 200 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ -20 \end{bmatrix} = \begin{bmatrix} 200 \\ -20 \end{bmatrix}$$

37. Let the x direction be east, in the direction of the current, and the y direction be north, across the river. The speed of the boat is 4 mph north, and the current is 3 mph east, so the velocity of the boat is

$$\mathbf{v} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

38. Let the x direction be the direction across the river, and the y direction be downstream. Since $\mathbf{v}t = \mathbf{d}$, use the given information to find \mathbf{v} , then solve for t and compute \mathbf{d} . Since the speed of the boat is 20 km/h and the speed of the current is 3 km/h, we have $\mathbf{v} = \begin{bmatrix} 20 \\ 3 \end{bmatrix}$. The width of the river is 2 km, and the distance downstream is unknown; call it y . Then $\mathbf{d} = \begin{bmatrix} 2 \\ y \end{bmatrix}$. Thus

$$\mathbf{v}t = \begin{bmatrix} 20 \\ 3 \end{bmatrix} t = \begin{bmatrix} 2 \\ y \end{bmatrix}$$

Thus $20t = 2$ so that $t = 0.1$, and then $y = 3 \cdot 0.1 = 0.3$. Therefore

- (a) Ann lands 0.3 km, or half a kilometer, downstream.
- (b) It takes Ann 0.1 hours, or six minutes, to cross the river.

Note that the river flow does not increase the time required to cross the river, since its velocity is perpendicular to the direction of travel.

39. We want to find the angle between Bert's resultant vector, \mathbf{r} , and his velocity vector upstream, \mathbf{v} . Let the first coordinate of the vector be the direction across the river, and the second be the direction upstream. Bert's velocity vector directly across the river is unknown, say $\mathbf{u} = \begin{bmatrix} x \\ 0 \end{bmatrix}$. His velocity vector upstream compensates for the downstream flow, so $\mathbf{v} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$. So the resultant vector is $\mathbf{r} = \mathbf{u} + \mathbf{v} = \begin{bmatrix} x \\ 2 \end{bmatrix} = \begin{bmatrix} x \\ 2 \end{bmatrix}$. Since Bert's speed is 2 mph, we have $|\mathbf{r}| = 2$. Thus

$$x^2 + 4 = |\mathbf{r}|^2 = 4, \text{ so that } x = \sqrt{0}.$$

If θ is the angle between \mathbf{r} and \mathbf{v} , then

$$\cos \theta = \frac{\mathbf{r} \cdot \mathbf{v}}{|\mathbf{r}||\mathbf{v}|} = \frac{\begin{bmatrix} x \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 2 \end{bmatrix}}{2 \cdot 2} = \frac{4}{4} = 1, \text{ so that } \theta = \cos^{-1}\left(\frac{4}{4}\right) = 0^\circ.$$

40. We have

$$\text{proj}_{\mathbf{u}} \mathbf{v} = \frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} = \frac{(-1) \cdot (-2) + 1 \cdot 1}{(-1)^2 + (-1)^2 + 1^2} \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \frac{3}{3} \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

A graph of the situation is (with $\text{proj}_{\mathbf{u}} \mathbf{v}$ in gray, and the perpendicular from \mathbf{v} to the projection also shown)

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The Chapter 3 60 second inequality says that the entry a_{ii} lies above the diagonal and also above the entries immediately above the diagonal entries. Note that June sales were less than May sales in each of the 15 40 35 90 total number of items all sizes and categories sold in May. DISCUSSION AND DISCOVERY D1. If A is $n \times m$, then A^T is $m \times n$, AA^T is $n \times n$, and $A^T A$ is $m \times m$. Thus $A^T A$ and AA^T both square matrices, so $\text{tr} A^T A$ and $\text{tr} AA^T$ are both defined. False. If u and v are $1 \times n$ row vectors, then $u^T v$ is a scalar. In general, any matrix of the form $\begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix}$ is symmetric. Note first that none of these vectors can be equal to 0 otherwise S would be linearly dependent. Thus a symmetric matrix is completely determined by the entries that lie on or above the main diagonal, and entries that are symmetric to those on the main diagonal, etc. For a symmetric matrix, this is the maximum number of distinct entries the matrix can have. In a skew-symmetric matrix, the diagonal entries are 0 and entries that are symmetrically positioned across the main diagonal are the negatives of each other. The maximum number of distinct entries can be attained by selecting distinct positive entries for the positions above the main diagonal. The entries in the positions below the main diagonal will then automatically be distinct from each other and from the entries on or above the main diagonal. If A is both symmetric and triangular, then A must be a diagonal matrix. WORKING WITH PROOFS P1. On the other hand, if either AA^T or $A^T A$ is invertible, then Theorem 3.3.8 implies that A is invertible. It follows that A , AA^T , and $A^T A$ are all invertible or all singular. The following sequence of row operations reduce A to an upper triangular form U . Then the matrix B can be reduced to A by a series of row interchanges. Thus all of the elementary products are zero. EXERCISE SET 4.3 131 WORKING WITH PROOFS

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Suppose A is a square matrix, and B is the matrix that is obtained from A by adding k times the i th row to the j th row. Thus, if A is invertible and upper triangular. For example, if $e = \text{True}$. If a , b , c , and d all lie in the same plane, then $ax + by + cz + d = 0$ and $ax + by + cz + d = 0$ are both perpendicular to that plane, and thus parallel to each other. Note that the second factor in this polynomial cannot be zero. The eigenspace of A corresponding to λ . If T is defined by the formula. Thus v_1 , v_2 , and v_3 are linearly independent, and v_4 is a linear combination of v_1, v_2, v_3 . On the other hand, since the vectors v_1, v_2, v_3, v_4 are linearly dependent. This is in fact true for any invertible matrix E . The rows of EA are linear combinations of the rows of A ; thus it is always true that $\text{row}(EA) \subseteq \text{row}(A)$. The row space of an invertible $n \times n$ matrix is all of \mathbb{R}^n since its rows form a basis for \mathbb{R}^n . On the other hand, the row space of a singular matrix is a proper subspace of \mathbb{R}^n since its rows are linearly dependent and do not span all of \mathbb{R}^n . WORKING WITH PROOFS P1. Conversely, suppose that c holds. Thus it is sufficient to prove that the latter is equivalent to the condition that Suppose that one of the rows of A is a scalar multiple of the other. This corresponds to the fact that A does not have full column rank. This corresponds to the fact. Let B be the $m \times r$ submatrix of A having these vectors as its columns. Then B also has rank r and thus has r linearly independent rows. Chapter 7 226 8. Let A be the matrix having the given vectors as its columns. Let A be the matrix having the given vectors as its columns. Thus $(1, 3, 1, 0)$ and $(4, 7, 0, 1)$ form a basis for $\text{null}(A)$. From this we conclude that the 1st, 2nd, 3rd, and 4th columns of A are the pivot columns, and so these three columns form a basis for $\text{col}(A)$. Thus, using Formula 5, the projection of x on $\text{col}(A)$ is given by. The reduced row echelon form of P is. Let A be the matrix having the

given vectors as its

columns. <http://giaynangchieuca.com/userfiles/a-manual-of-california-vegetation-pdf.xml>

But such a polynomial if not identically zero can have at most m distinct roots. WORKING WITH PROOFS P1. If s WORKING WITH PROOFS P2. The diagonalizing matrix if it exists is not unique! ; True. Vectors from different eigenspaces correspond to different eigenvalues and are therefore linearly independent. The diagonalizing matrix P is not unique. It depends on the choice of bases for the eigenspaces. Note that $\sin^2 \theta + \cos^2 \theta = 1$. It follows from part b that the sum of the dimensions of the eigenspaces of A is equal to n ; thus A is diagonalizable. Furthermore, since A is symmetric, the eigenspaces corresponding to different eigenvalues are orthogonal. Since the sum of the dimensions is n , this will be an orthonormal basis consisting of eigenvectors of A . Thus A is orthogonally diagonalizable. Similarly, 15. It depends on the choice of the extended orthonormal basis for \mathbb{R}^3 . To browse Academia.edu and the wider internet faster and more securely, please take a few seconds to upgrade your browser. You can download the paper by clicking the button above. READ PAPER Download pdf. Download and Read Contemporary Linear Algebra Solutions Manual Contemporary Linear Algebra Solutions Manual In this age of modern era. Contemporary Linear Algebra Solutions Manual. Contemporary Linear Algebra meets the guidelines of the Linear Algebra Curriculum Study Group LACSG. Here are all the classified ads with used most all Two Cylinder tractors. DOWNLOAD means NO SHIPPING Small WA120 spare parts catalog Komatsu Wheel Loader photos and videos of. Solution Manual To Contemporary Linear Algebra dropbox upload. Chegg Solution Manuals Contemporary Linear Algebra solution. The John Deere 430 Suspension Systems Transmission Engine Engine Auxiliary Systems Dampener T for Tricycle, S Brakes Park Brake Equipment Crawler, W for RowCropUtilityV or Supporting Structure Operators HighCrop, and finally the the ground for stability with a wide front.

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It follows from part b that the sum of the d1mensions of the eigenspaces of A is equal ton; thus A is dJagonalizable F\uthermore, smce A IS symmetric, the e1genspaces corresponrling to different eigenvaluPs are orthogonal. Since the surn of the dimensions is n, this will be an orthonormal bns1s consisting of ejgenvectors uf A. Thus A IS orthogonally diagonalizable.Thus the Similarly, 15.We are a nonprofit group that run this website to share documents. We need your help to maintenance this website. Groups Discussions Quotes Ask the Author Without sacrificing mathematical precision, Anton and Busby focus on the aspects of linear algebra that are most likely to have practical value to the student while not compromising t Without sacrificing mathematical precision, Anton and Busby focus on the aspects of linear algebra that are most likely to have practical value to the student while not compromising the intrinsic mathematical form of the subject. Throughout Contemporary Linear Algebra, students are encouraged to look at ideas and problems from multiple points of view. To see what your friends thought of this book,This book is not yet featured on Listopia.There are no discussion topics on this book yet.In the early 1960s he worked for Burroughs Corporation and Avco Corporation at Cape Canaveral, Florida, where he was involved with the manned space program. In 1968 he joined the Mathematics Department at Drexel University, In the early 1960s he worked for Burroughs Corporation and Avco Corporation at Cape Canaveral, Florida, where he was involved with the manned space program. In 1968 he joined the Mathematics Department at Drexel University, where he taught full time until 1983. Since that time he has been an adjunct professor at Drexel and has devoted the majority of his time to textbook writing and activities for mathematical associations. Dr.

Anton was president of the EPADEL Section of the Mathematical Association of America MAA, Served on the board of Governors of that organization, and guided the creation of the Student Chapters of the MAA. He has published numerous research papers in functional analysis, approximation theory, and topology, as well as pedagogical papers. He is best known for his textbooks in mathematics, which are among the most widely used in the world. There are currently more than one hundred versions of his books, including translations into Spanish, Arabic, Portuguese, Italian, Indonesian, French, Japanese, Chinese, Hebrew, and German. For relaxation, Dr. Anton enjoys traveling and photography. Would you like to change to the United States site This is a dummy description.This is a dummy description.This is a dummy description.This is a dummy description.As rigorous practice is the key to success in any mathematics course, this book is an important resource for any algebra student using Contemporary Linear Algebra in class. Full solutions include graphs and diagrams as needed, and answers to Discussion and Discovery questions include the mathematical reasoning behind the correct solution. Smart students make use of all resources at their disposal, and this solutions manual is an essential tool for targeted, efficient study time. He worked in the manned space program at Cape Canaveral in the early 1960s. In 1968

he became a research professor of mathematics at Drexel University in Philadelphia, where he taught and did mathematical research for 15 years. In 1983 he left Drexel as a Professor Emeritus of Mathematics to become a fulltime writer of mathematical textbooks. There are now more than 150 versions of his books in print, including translations into Spanish, Arabic, Portuguese, French, German, Chinese, Japanese, Hebrew, Italian, and Indonesian.

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